

## **FEATURES**

- Speed regulation of  $< \pm 0.001\%$  can be achieved with precision spindles and feedback devices
- Controls brushless motors over a wide speed range 100 to over 50,000 RPM
- Switching frequency of 24 to 80KHz allows operation with low inductance motors
- Accepts external or internal frequency (speed) command
- Frequency synthesizer circuits provide a programmable frequency (speed) command from a precise crystal reference
- Velocity feedback can be derived from the motor commutation sensors, incremental encoder, or a laser scanner
- Digital inputs for Enable/Reset, Brake, Internal/External frequency command, and Direction of rotation
- Output current is adjustable to 10 amperes peak
- Drives three phase delta or wye connection stators
- Operates from one low cost unregulated DC power supply

### **APPLICATIONS**

- Laser scanners
- High-speed air bearing spindles
- High accuracy machining and grinding
- Memory disk and head testers
- Wafer spinners
- Centrifuge



### **PRODUCT DESCRIPTION**

This size 3U EUROCARD provides precise phase lock loop control of the speed of permanent magnet brushless DC motors.

The controller was designed to provide easy setup. The servo loop gain and compensation are pre-configured at the factory for the most demanding applications. Plug able jumpers can set many of the operating features.

The high efficiency switch mode power output stage employs a four-quadrant PWM drive scheme, which minimizes EMI in noise sensitive applications. It also improves motor efficiency by reducing copper and iron losses in the motor. A switching frequency of 24 to 80KHz excludes audible noise, and allows a wide control bandwidth in the current feedback loop.

The controller employs time dependent peak current limiting. A trim potentiometer allows adjustment of the peak current up to the maximum value.

Fault protection circuits will detect and disable the power output stage for over temperature, over speed, over voltage, current overload, and motor stall. Logic output signals and LED indicators provide fault indication.

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MODEL	5-559-048-00	5-149-024-00	
Input Power Bus (Vbus) <sup>2</sup>	40 to 55 VDC	21 to 35 VDC	
Continuous Output Power (Max.)	260 Watts <sup>1</sup>	160 Watts <sup>1</sup>	
Continuous Output Current	5 Amps <sup>1</sup>	5 Amps <sup>1</sup>	
Peak Output Current	10 Amps (3 Sec) <sup>1</sup>	10 Amps (3 Sec) <sup>1</sup>	
Out Voltage @ Continuous Output Current	Vbus - 3 volts	Vbus - 3 volts	
Minimum load inductance	200 uH	100Uh	
Maximum Heat Sink Temperature	Drive Disables if >70 ° C		
Power Amplifier	Switch Mode Drive		
Switching Frequency	Adjustable from 24KHz to 80KHz		
Current Loop Bandwidth	2 KHz Typical		
Operating Temperature	0 to 50 ° C		
Logic Supply	5 VDC developed internally		
Weight	.45 Kg (1 Lb)		

## **GENERAL SPECIFICATIONS**

### OPERATING CONTROL SIGNALS and INDICATORS

Speed command is proportional to input	5V Square wave - Scale Factor in RPM/Hz	
internal or external frequency		
Plug able jumpers programs internal	5V logic	
frequency Command		
Select internal or external frequency	5V logic or PCB jumper	
command		
Select velocity feedback source	PCB jumper	
Select direction of rotation	PCB jumper	
Peak current limit	Adjustable	
Drive Enable/Reset	5V logic or PCB switch	
Speed @ Lock	5V logic signal and LED	
Fault Status	5V logic signal and LED	
Current Fault	5V logic	
Temperature Fault	5V logic signal and LED	
Over Voltage	5V logic signal and LED	

## FAULT PROTECTION CIRCUITS

Controller over temperature Current overload Illegal Hall sensor input Under voltage Over speed Motor Stall

#### Notes:

- 1. Depends on ambient operating temperature and heat sink. For the rated continuous power output, forced convection cooling with a minimum airflow of 100 CFM is required. Consult factory for assistance.
- 2. The user should protect the Amplifier and any external circuits from a catastrophic failure by fusing the input power connections to the amplifier. See Application Note Supplementary Fuse Protection.

#### **EXTERNAL SIGNALS AND INTERCONNECTIONS**

EDGE CONNECTOR J1 IS A 25 CONTACT MALE D-SUB

TERMINAL	SIGNAL NAME	DESCRIPTION	
J1-1	ENCODER FEEDBACK	5VDC LOGIC	
J1-2	ENCODER SHIELD	ENCODER SHIELD GND	
J1-3	SELECT INT/EXT FREQ CMD	LOGIC 0=EXTERNAL FREQUENCY COMMAND, <5>	
J1-4	EXT FREQ (SPEED) CMD	5V SQ WAVE, FREQUENCY COMMAND SF=RPM/HZ<1>	
J1-5	MTR PHASE B	OUTPUT TO MOTOR PHASE B WINDING	
J1-6	MTR PHASE B	OUTPUT TO MOTOR PHASE B WINDING	
J1-7	MTR PHASE A	OUTPUT TO MOTOR PHASE A WINDING	
J1-8	MTR PHASE A	OUTPUT TO MOTOR PHASE A WINDING	
J1-9	MTR PHASE C	OUTPUT TO MOTOR PHASE C WINDING	
J1-10	MTR PHASE C	OUTPUT TO MOTOR PHASE C WINDING	
J1-11	MTR SHIELD	MOTOR SHIELD GND	
J1-12	VDC POWER BUS IN	POWER SUPPLY INPUT <2>, <6>	
J1-13	VDC POWER BUS IN	POWER SUPPLY INPUT <2>, <6>	
J1-14	ENABLE/RESET	LOGIC 0=ENABLE, <3>	
J1-15	SPEED LOCK	LOGIC 0=SPEED LOCK,<4>	
J1-16	GROUND	DC RTN	
J1-17	HALL SENSOR POWER	5VDC OUT, 20 MILLAMPS MAX LOAD	
J1-18	HALL SENSOR POWER RTN	DC RTN	
J1-19	FAULT OUT	LOGIC 0 =FAULT <4>	
J1-20	S1 HALL SENSOR IN	5V LOGIC	
J1-21	S2 HALL SENSOR IN	5V LOGIC	
J1-22	S3 HALL SENSOR IN	5V LOGIC	
J1-23	HALL SENSOR SHIELD	HALL CABLE SHIELD GND	
J1-24	VDC POWER BUS RETURN	POWER SUPPLY RETURN	
J1-25	VDC POWER BUS RETURN	POWER SUPPLY RETURN	

NOTES:

<1> INTERNAL 100K PULL-UP RESISTOR TO 5VDC.

<2> CONSULT FACTORY IF USING A REGULATED SUPPLY

- <3> SWITCH S1 ON PCB IS IN SERIES WITH THIS LOGIC INPUT CMD. INSTALLATION OF JUMPER JP2 WILL DISABLE THE EXTERNAL CMD.
- <4> OUTPUT FROM OPEN COLLECTOR, WITH 10K PULL-UP.
- <5> LOGIC INPUT TO SELECT INTERNAL OR EXTERNAL FREQUENCY (SPEED) COMMANDS. LOGIC "1" IS THE DEFAULT STATE. GROUND THIS INPUT OR INSTALL JUMPER JP20 TO PROGRAM THE LOGIC TO ACCEPT AN EXTERNAL INPUT FREQUENCY (SPEED) COMMAND.
- <6> SEE APPLICATION NOTE SUPPLEMENTARY FUSE PROTECTION.



### COMMUTATION DIAGRAM

ROTOR POSITION ELECTRICAL DEGREES



Date:	Wednesday, October 02, 2002 Sheet 1	of	· 1
Size	Document Number		Rev A
Title	COMMUTATION DIAGRAM		
	CARLSBAD, CA		
	ELTROL CORPORATION		

