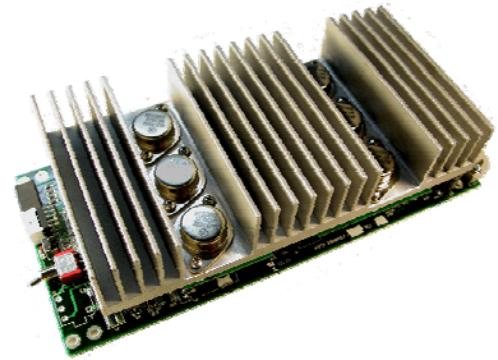


### FEATURES

- High performance Linear Servo Amplifier controls DC brush motor torque and linear motor or voice coil force
- Linear operating mode does not emit EMI, has high servo stiffness, and no dead zone
- DSP platform provides intelligent control, programmable configuration, fault protection, self-test, calibration, and status reporting
- Current loop bandwidth and transconductance, (amps/volt scale factor) are adjustable
- Fault protection for amplifier SOA, over and under voltage, temperature, current overloads, and motor shorts
- Seven-segment LED display shows drive status
- Complete operating and fault status via RS-232
- Provides streaming data via I<sup>2</sup>C interface
- System configuration parameters are input digitally via HyperTerminal
- Digital inputs for Enable/Reset, and 4 programmable for Brake, DIR,  $\pm$ Travel Limits
- Offsets are digitally trimmed, providing greater precision and stability than traditional pots
- Operates with low inductance motors
- High and low supply voltage versions and high and low power versions
- Operates from one regulated or unregulated DC power supply with internal  $\pm$  12V DC-DC converter

### APPLICATIONS

- Linear stages, air bearings, and gantry systems
- Semiconductor metrology
- High accuracy assembly/measurement
- Active isolation systems
- Optical positioning and scanners



### PRODUCT DESCRIPTION

This size 3U EUROCARD provides closed loop four quadrant force or torque control of DC brush rotary servo motors, torque motors, linear motors, and voice coil actuators.

Linear control of DC brush or linear motors is especially important for high performance position or velocity control systems. The pure DC form factor allows high current loop bandwidth.

The linear operating mode is highly advantageous for noise sensitive applications because it does not generate EMI. PWM switching noise is difficult to eliminate from sensitive sensors and transducers, and degrades velocity and position accuracy.

Excessive power dissipation is the main reliability consideration for linear amplifier operation. This model uses a digital signal processor (DSP) to monitor the safe operating area (SOA) of the output devices to prevent them from overheating and failing.

**LOW VOLTAGE MODELS  
GENERAL SPECIFICATIONS**

<b>ELTROL MODEL# →</b>	<b>6-900-048-57I</b>	<b>6-360-048-57J</b>
POWER AMPLIFIER	Linear DC Drive	Linear DC Drive
PEAK OUTPUT POWER	900 watts <sup>1</sup>	360 watts <sup>1</sup>
PEAK OUTPUT CURRENT	25 amps <sup>1</sup> (1 sec typ.)	10 amps <sup>1</sup> (1 sec typ.)
CONT. OUTPUT CURRENT	Note 1	Note 1
MAX AMPLIFIER DISSIPATION	200 watts <sup>1</sup>	150 watts <sup>1</sup>
OUTPUT VOLTAGE @ PEAK CURRENT	40V with 48V Nominal bus	41V with 48V Nominal bus
INPUT POWER BUS <sup>6</sup>	24 to 60 VDC	24 to 60 VDC
ANALOG SUPPLY <sup>2</sup>	+12 VDC/ 0.2AMPS MAX	+12 VDC/ 0.2AMPS MAX
ANALOG SUPPLY <sup>2</sup>	-12 VDC/ 0.2AMPS MAX	-12 VDC/ 0.2AMPS MAX
LOGIC SUPPLY <sup>2</sup>	5 VDC / 0.3 AMPS MAX	5 VDC / 0.3 AMPS MAX
INPUT CONTROL LOGIC	Optional 5V or 3.3V	Optional 5V or 3.3V
COMMAND SIGNAL INPUT	± 10V differential	± 10V differential
OPERATING TEMPERATURE	0 TO 50 Degrees C <sup>1</sup>	0 TO 50 Degrees C <sup>1</sup>
CURRENT COMMAND S.F.	2.5 or 2 AMP/VOLT	1 or 0.5 AMP/VOLT
CURRENT LOOP BANDWIDTH	Adjustable 0.5 to 4 KHZ	Adjustable 0.5 to 4 KHZ
SIZE	100 W x 220 L x 56 H mm	100 W x 220 L x 45 H mm
WEIGHT	.87 kg (1.92 lb)	.69 kg (1.53 lb)

**HIGH VOLTAGE MODELS  
GENERAL SPECIFICATIONS**

<b>ELTROL MODEL# →</b>	<b>6-1400-080-57K</b>	<b>6-700-080-57L</b>
POWER AMPLIFIER	Linear DC Drive	Linear DC Drive
PEAK OUTPUT POWER	1400 watts <sup>1</sup>	700 watts <sup>1</sup>
PEAK OUTPUT CURRENT	20 amps <sup>1</sup> (1 sec typ.)	10 amps <sup>1</sup> (1 sec typ.)
CONT. OUTPUT CURRENT	Note 1	Note 1
MAX AMPLIFIER DISSIPATION	200 watts <sup>1</sup>	150 watts <sup>1</sup>
OUTPUT VOLTAGE @ PEAK CURRENT	73V with 80V Nominal bus	73V with 80V Nominal bus
INPUT POWER BUS <sup>6</sup>	36 to 85 VDC	36 to 85 VDC
ANALOG SUPPLY <sup>2</sup>	+12 VDC/ 0.2AMPS MAX	+12 VDC/ 0.2AMPS MAX
ANALOG SUPPLY <sup>2</sup>	-12 VDC/ 0.2AMPS MAX	-12 VDC/ 0.2AMPS MAX
LOGIC SUPPLY <sup>2</sup>	5 VDC / 0.3 AMPS MAX	5 VDC / 0.3 AMPS MAX
INPUT CONTROL LOGIC	Optional 5V or 3.3V	Optional 5V or 3.3V
COMMAND SIGNAL INPUT	± 10V differential	± 10V differential
OPERATING TEMPERATURE	0 TO 50 Degrees C <sup>1</sup>	0 TO 50 Degrees C <sup>1</sup>
CURRENT COMMAND S.F.	2.5 or 2 AMP/VOLT	1 or 0.5 AMP/VOLT
CURRENT LOOP BANDWIDTH	Adjustable 0.5 to 4 KHZ	Adjustable 0.5 to 4 KHZ
SIZE	100 W x 220 L x 56 H mm	100 W x 220 L x 45 H mm
WEIGHT	.87 kg (1.92 lb)	.69 kg (1.53 lb)

**OPERATING CONTROL SIGNALS and INDICATORS**

Input analog control signal <sup>4</sup>	± 10 Volts differential
Peak current limit	Adjustable
Drive Enable/Reset	5V logic or 3.3V
Programmable digital inputs (4):	5V logic or 3.3V
Direction Logic	
(+) Travel Limit	
(-) Travel Limit	
Brake <sup>4</sup>	
Amplifier Status indicator	Seven Segment LED

**AUXILIARY OUTPUTS**

Motor current monitor:	Analog Signal
Drive status 4 outputs:	Digital (mutually exclusive with I <sup>2</sup> C)
Drive fault:	Digital

**SERIAL I/O**

RS232  
I<sup>2</sup>C

**FAULT PROTECTION CIRCUITS**

Safe Operating Area Protection  
Short circuit  
Over temperature <sup>6</sup>  
Over current <sup>6</sup>  
Over / under voltage

**NOTES:**

1. Depends on ambient operating temperature, motor winding resistance, and heat sink airflow. For the rated maximum controller power dissipation, forced convection cooling with a minimum airflow of 200 CFM is required.

De-rate at 1.7 watts/degree C for ambient greater than 30 degrees C.

Maximum controller dissipation occurs when the power out is minimum (motor stalled).

It can be calculated as follows:

$$P_d = P_{in} - P_{mtr}$$

$$P_{in} = (V_s)(I_o)$$

$$P_{mtr} = (I_o)^2(R_t)$$

Where

$P_d$  is controller dissipation in watts

$P_{mtr}$  is motor dissipation in watts

$V_s$  is supply voltage

$I_o$  is the average output current in amps

$R_t$  is motor terminal-to-terminal resistance for a wye winding in ohms.

2. Developed internally from on-board dc-dc converter.
3. Actuating brake at high motor speeds may damage the controller or motor. Consult factory for details.
4. Over temperature or over current protection is determined from the DSP monitoring of amplifier operating heat sink temperature and output device power dissipation magnitude versus time. When power device junction over temperature protection is activated, the amplifier output will be disabled. A fault report is available via the RS232 port.
5. The user should protect the Amplifier and any external circuits from a catastrophic failure by fusing the input power connections to the amplifier. See Application Note Supplementary Fuse Protection (which can be viewed at [www.peakservo.com](http://www.peakservo.com)).

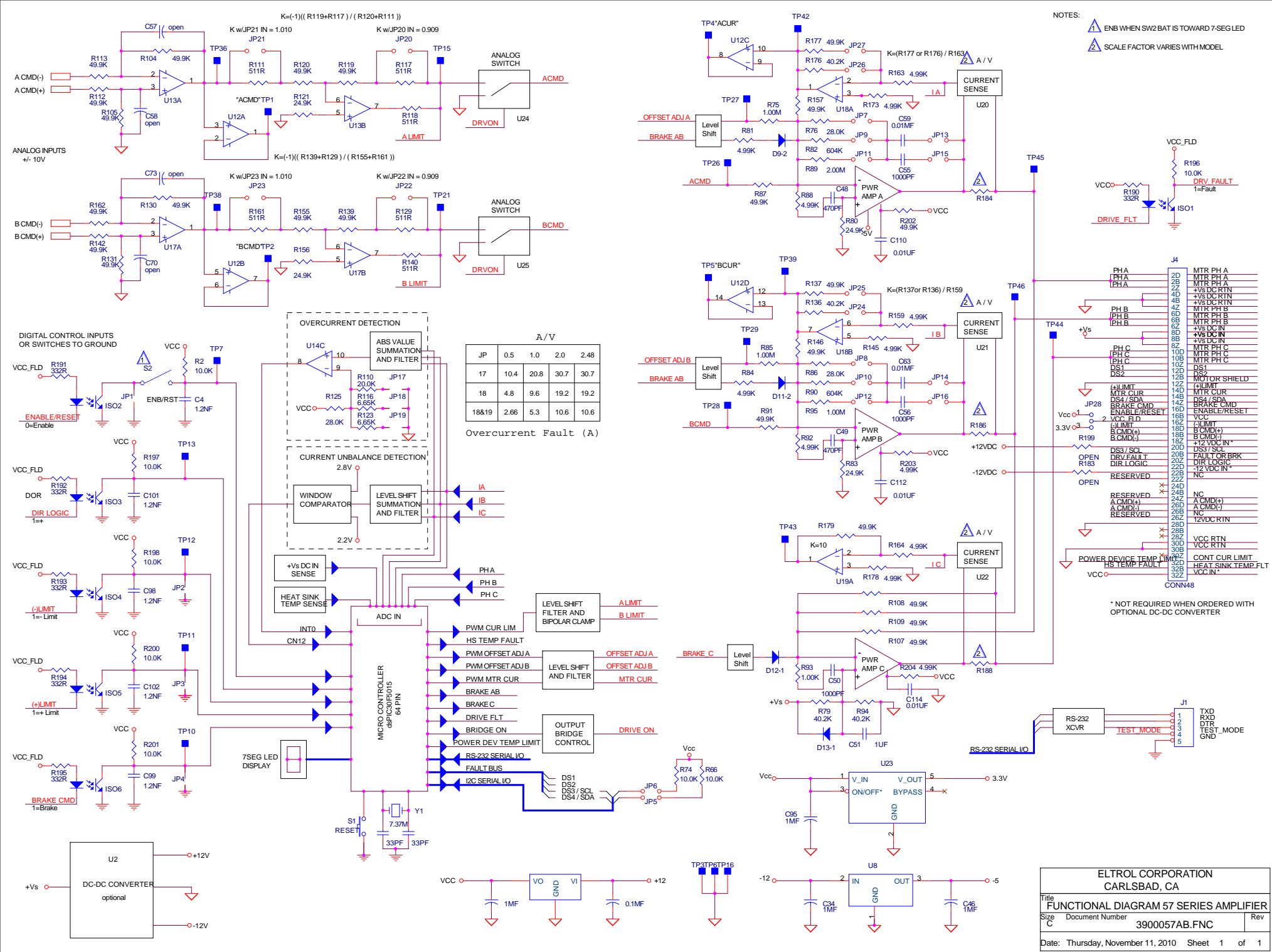
### EXTERNAL SIGNALS AND INTERCONNECTIONS

EDGE CONNECTOR J4 IS A 48 POLE DIN 41612 SERIES F  
(REF EPT P/N 109-40064) or (FCI P/N 5159009486394111)

TERMINAL	SIGNAL NAME	DESCRIPTION
J4-2D, B, Z	MTR (+)	OUTPUT TO MOTOR (+) TERMINAL
J4-4D, B, Z	VDC POWER BUS RETURN	POWER SUPPLY RETURN
J4-6D, B, Z	NC	NO CONNECTION
J4-8D, B, Z	VDC POWER BUS IN	POWER SUPPLY INPUT, <10>
J4-10D, B, Z	MTR (-)	OUTPUT TO MOTOR (-) TERMINAL
J4-12D	DS1	DRIVE STATUS CODE <7><12>
J4-12B	DS2	DRIVE STATUS CODE <7><12>
J4-12Z	MTR SHIELD	MOTOR SHIELD GND
J4-14D	(+) LIMIT	LOGIC 1= (+) LIMIT, <1>, <3>
J4-14B	MTR CUR	MOTOR CURRENT MONITOR (SEE SECT. 6.0)
J4-14Z	DS4 / SDA	DRIVE STATUS CODE <7> / I <sup>2</sup> C <10><12>
J4-16D	BRAKE CMD	LOGIC 1= BRAKE, <1>, <5>
J4-16B	ENABLE/RESET	LOGIC 0=ENABLE, <1>, <2>
J4-16Z	Vcc OUT	5VDC OUT
J4-18D	(-) LIMIT	LOGIC 1= (-) LIMIT, <1>, <4>
J4-18B	NC	NO CONNECTION
J4-18Z	NC	NO CONNECTION
J4-20D	+12VDC IN	12 V POWER SUPPLY INPUT <9>
J4-20B	DS3 / SCL	DRIVE STATUS CODE <7> / I <sup>2</sup> C <10><12>
J4-20Z	DRIVE FAULT	LOGIC 1= FAULT <8>
J4-22D	DIR LOGIC	INPUT FROM MOTION CONTRL, LOGIC 1=(+) DIRECTION<1>
J4-22B	(-) 12VDC IN	(-) 12 V POWER SUPPLY INPUT <9>
J4-22Z	NC	RESERVED
J4-24D	NC	NO CONNECTION
J4-24B	NC	NO CONNECTION
J4-24Z	NC	RESERVED
J4-26D	A COMMAND (+)	DIFFERENTIAL ANALOG ± 10V A INPUT COMMAND, <6>
J4-26B	A COMMAND (-)	DIFFERENTIAL ANALOG ± 10V A INPUT COMMAND, <6>
J4-26Z	NC	RESERVED
J4-28D	±12V RTN	±12V POWER SUPPLY RETURN
J4-28B	NC	NO CONNECTION
J4-28Z	NC	NO CONNECTION
J4-30D, B	Vcc RTN	5VDC RTN
J4-30Z	NC	NO CONNECTION
J4-32D	CC LIMIT	CC LIMIT, LOGIC 1=CC FAULT <12>
J4-32B	AMP TEMPERATURE FAULT	LOGIC 1=HEAT SINK TEMPERATURE FAULT <7><11><12>
J4-32Z	+5VDC IN	5 V POWER SUPPLY INPUT <9>

NOTES:

- <1> OPTICALLY ISOLATED INPUT WITH INTERNAL 332 OHM PULL-UP RESISTOR TO 5VDC. SEE FUNCTIONAL DIAGRAM.
- <2> SWITCH S1 ON PCB IS IN SERIES WITH THIS LOGIC INPUT CMD. INSTALLATION OF JUMPER JP1 WILL DISABLE THE EXTERNAL CMD.
- <3> (+) LIMIT IS THE TRAVEL LIMIT THE MOTOR WILL DRIVE TOWARD WHEN THE DIRECTION SIGNAL IS A LOGIC 1. INSTALLATION OF JUMPER JP3 WILL DISABLE THIS FEATURE.
- <4> (-) LIMIT IS THE TRAVEL LIMIT THE MOTOR WILL DRIVE TOWARD WHEN THE DIRECTION SIGNAL IS A LOGIC 0. INSTALLATION OF JUMPER JP2 WILL DISABLE THIS FEATURE.
- <5> WHEN ACTIVE, THE MOTOR WINDINGS ARE SHORTED TOGETHER. IF THE BRAKE FEATURE IS NOT REQUIRED, INSTALL JUMPER JP4. CAUTION: BRAKE CMD AT HIGH SPEED MAY DAMAGE MOTOR AND/OR CONTROLLER. CONSULT FACTORY FOR ASSISTANCE.
- <6> COMMAND POLARITY DETERMINES DIRECTION OF MOTION, SIGNAL AND SIGNAL RETURN CAN BE EXCHANGED. SEE <3>, <4>.
- <7> OUTPUT FROM DIGITAL PROCESSOR. SEE DRIVE STATUS CODE TABLE. 0=TTL LOW, Z=HIGH IMPEDANCE.
- <8> OUTPUT FROM OPTO ISOLATOR. SEE FUNCTIONAL DIAGRAM.
- <9> NOT REQUIRED WHEN OPTIONAL DC-DC CONVERTER IS ORDERED.
- <10> IF I<sup>2</sup>C IS ENABLED, THESE PINS ARE USED WITH I<sup>2</sup>C IN LIEU OF FAULT BUS OUTPUT.
- <11> LIMIT SINK CURRENT TO  $\leq 1\text{ma}$ . JUNCTION TEMP  $>120\text{C}$ , HEAT SINK  $>70\text{C}$
- <12> LIMIT SINK CURRENT TO  $\leq 1\text{ma}$ .



NOTES:

- ENB WHEN SW2 BAT IS TOWARD 7-SEG LED
- SCALE FACTOR VARIES WITH MODEL

J4

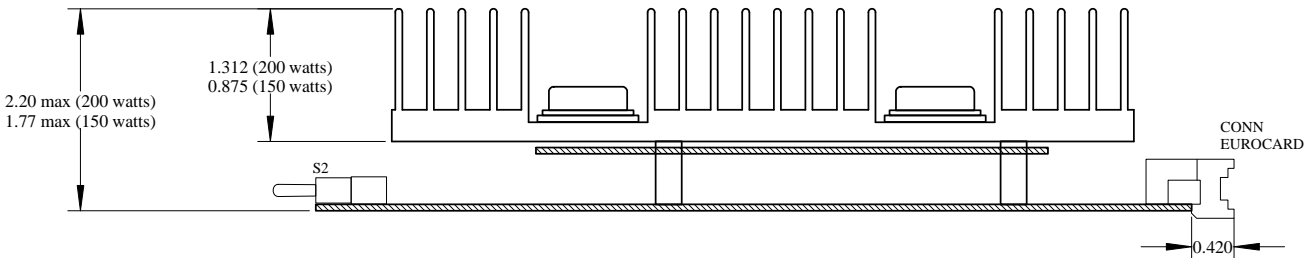
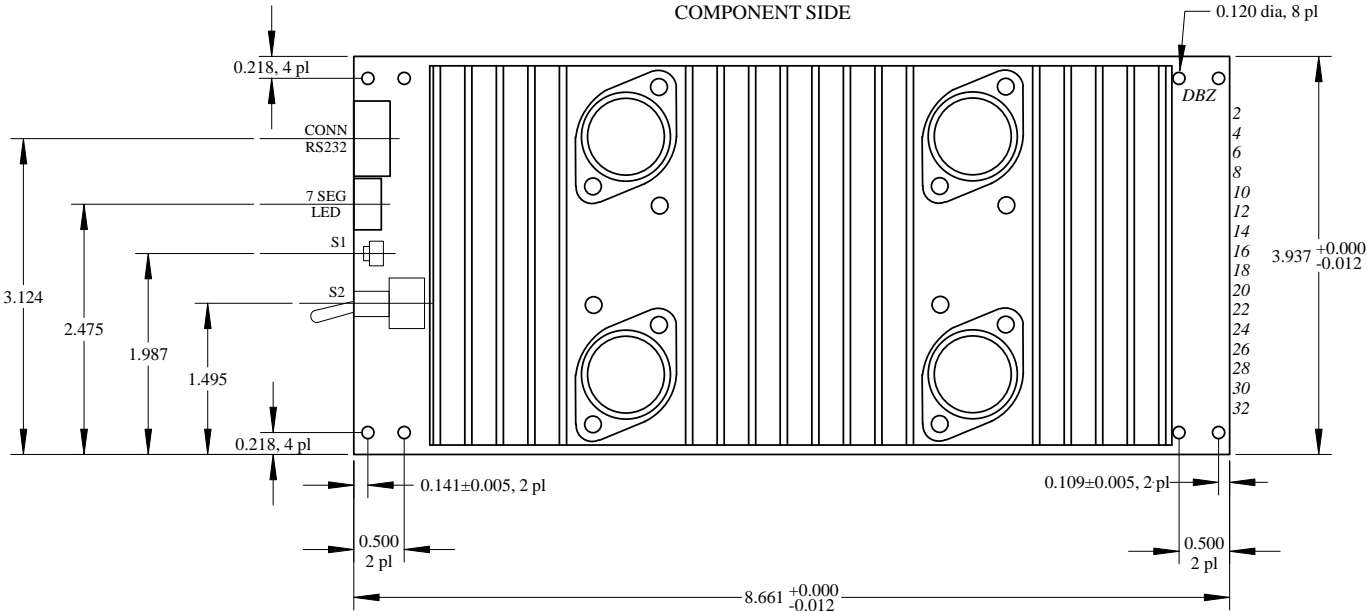
2D	MTR PH A
2E	MTR PH A
4D	+V5 DC RTN
4B	+V5 DC RTN
4C	+V5 DC IN
6D	MTR PH B
6E	MTR PH B
6F	+V5 DC IN
8D	+V5 DC IN
8E	MTR PH C
10D	MTR PH C
10E	MTR PH C
12D	DS1
12E	DOCTOR SHIELD
12F	(+LIMIT
14D	MTR CUR
14E	DS4/SDA
14F	BRAKE CMD
16D	ENABLE/RESET
16E	VCC
18D	(-LIMIT
18E	B CMD(+)
18F	B CMD(-)
20D	+12VDC IN
20E	DIR LOGIC
20F	FAULT OR BRK
22D	DIR LOGIC
22E	+12VDC IN
22F	NC
24D	NC
24E	MTR CUR
24F	DS4/SDA
26D	A CMD(+)
26E	A CMD(-)
26F	NC
28D	+12VDC RTN
28E	VCC RTN
28F	VCC RTN
30D	CONT CUR LIMIT
30E	HEAT SINK TEMP FLT
30F	VCC IN
32D	NC
32E	NC
32F	NC

\* NOT REQUIRED WHEN ORDERED WITH OPTIONAL DC-DC CONVERTER



# EUROCARD SERIES 57 LINEAR DC SERVO AMPLIFIER

## MOUNTING DIMENSIONS



- NOTES:
1. ALL DIMENSIONS SPECIFIED IN INCHES
  2. ALL DIMENSIONS ARE +/- .002 UNLESS OTHERWISE SPECIFIED
  3. DO NOT SCALE

<b>PEAK SERVO CORPORATION</b>	
CARLSBAD, CA	
Title	
SERIES 57 LINEAR DC AMP OUTLINE	
Document Number	Rev
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January 14, 2010	Sheet 1 of 1